

ICCAS 2022 Session Timetable

3F					1F						
Room 1 (322)	Room 2 (323)	Room 3 (324)	Room 4 (325)	Room 5 (326)	Room 6 (121)	Room 7 (122)	Room 8 (123)	Room 9 (124)	Room 10 (125)	Room 11 (126)	
November 27 (Sunday)											
13:00-18:00	Workshop: CubeSat Design, Development, and Operation (3F 326)										
18:00-19:00	Welcome Reception										
November 28 (Monday)											
09:00 ~ 10:30	MA1	MA2	MA3	MA4	MA5	MA6	MA7	MA8	MA9	MA10	MA11
	Artificial Neural Networks and Applications I	Autonomous Vehicle Systems I	Control Theory and Applications I	Guidance, Navigation, and Control I	Industrial Applications of Control I	SICE-ICROS Joint Organized Session : Robot Technology and Its Application	Image Processing I	Reinforcement Learning	Industrial Control Applications	Human Robot Interaction I	Manipulation and Motion Planning
10:30-10:40	Break										
10:40-11:30	Opening Ceremony & Plenary Lecture I (Prof. Bong Wie, USA) - 3F 5A Hall										
11:30-13:20	Lunch										
13:20-14:50	Industry-invited Session (Korean) 1- 3F 5A Hall [MP] Poster Session 1 - 3F Lobby										
14:50-15:00	Break										
15:00-15:50	Plenary Lecture II (Prof. Rolf Findeisen, Germany) - 3F 5A Hall										
15:50-16:00	Break										
16:00 ~ 17:30	MB1	MB2	MB3	MB4	MB5	MB6	MB7	MB8	MB9	MB10	MB11
	Artificial Neural Networks and Applications II	Autonomous Vehicle Systems II	Control Theory and Applications II	Guidance, Navigation, and Control II	Industrial Applications of Control II	SICE-ICROS Joint Organized Session : Robot Technology and Its Application	Image Processing II	Image Processing III	Control Devices and Instruments	Human Robot Interaction II	Sliding Mode Control
November 29 (Tuesday)											
09:00 ~ 10:30	TA1	TA2	TA3	TA4	TA5	TA6	TA7	TA8	TA9	TA10	TA11
	Artificial Neural Networks and Applications III	Unmanned Aerial Vehicles I	Control Theory and Applications III	Guidance, Navigation, and Control III	Kinematics and Dynamics of Robots	Smart Mobile Robots	Advances in Process Systems Engineering	Sensors and Actuators I	Recent Advances in Control Theory and Application	Applications of Robotic Technologies	Smart Manufacturing System
10:30-10:40	Break										
10:40-11:30	Plenary Lecture III (Prof. Yoon Young Kim, Korea) - 3F 5A Hall										
11:30-13:20	[NRF] Briefing Session on Basic Research Program for Researcher	Lunch									
13:20-14:50	Industry-invited Session (Korean) 2 - 3F 5A Hall [TP] Poster Session 2 - 3F Lobby										
14:50-15:00	Break										
15:00-15:50	Plenary Lecture IV (Prof. Henrik Sandberg, Sweden) - 3F 5A Hall										
16:00-18:00	[Workshop] Control and Operations of Microgrid	TB3									
		Recent Topics in Networked and Robust Control									
18:40-20:20	Banquet										
November 30 (Wednesday)											
09:00 ~ 10:30	WA1	WA2	WA3	WA4		WA6	WA7	WA8	WA9	WA10	WA11
	Deep Learning and Machine Vision Applications I	Unmanned Aerial Vehicles II	Control Theory and Applications IV	Agricultural and Construction Robotics I		ICROS and ECTI Organized Session on Advanced Control Designs and Applications	Service and Social Robotics	Sensors and Actuators II	Machine Learning and Applications	Machine Vision and Perception	Model-based Control and Signal Processing: Theory and Applications I
10:30-10:40	Break										
10:40-11:30	Plenary Lecture V (Prof. Maurizio Porfiri, USA) - 3F 5A Hall										
11:30-13:20	Lunch										
13:20-14:50	Industry-invited Session (Korean) 3 - 3F 5A Hall [WP] Poster Session 3 -3F Lobby										
14:50-15:00	Break										
15:00-15:50	Plenary Lecture VI (Prof. Hiroshi Fujimoto, Japan) - 3F 5A Hall										
15:50-16:00	Break										
16:00 ~ 17:30	WB1	WB2	WB3	WB4	WB5	WB6	WB7	WB8	WB9	WB10	WB11
	Deep Learning and Machine Vision Applications II	Autonomous Navigation and SLAM	Identification and Estimation	Agricultural and Construction Robotics II	Cyber Physical Systems	Multi-agent Systems	Advanced Navigation Technology & Application I	Recent Advances in Microrobotics Toward Medical Applications	Medical Robot and Simulation with Augmented Intelligence and Autonomy	Bio & Ecological Systems	Model-based Control and Signal Processing: Theory and Applications II
December 01 (Thursday)											
09:00-13:00	Technical Tour										